

Elimination theory, sparse systems and applications

Carlos D'Andrea

Journées Nationales de Calcul Formel – Luminy, March 2020

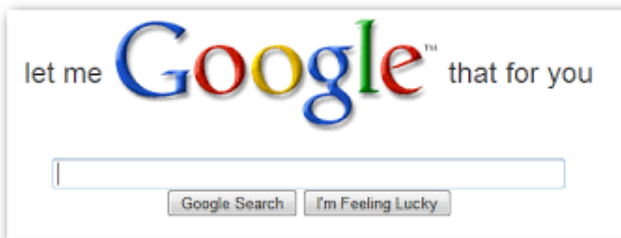


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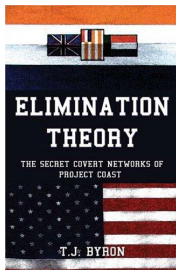
What is Elimination Theory?

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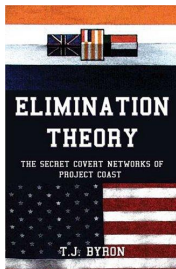


Elimination Theory

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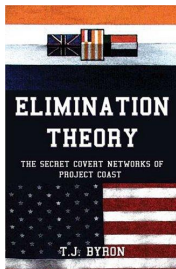
Elimination Theory



$\text{Res}(f(x), g(x)) =$

$$\begin{vmatrix} a_n & a_{n-1} & \cdots & a_1 & a_0 & 0 & \cdots & 0 \\ 0 & a_n & a_{n-1} & \cdots & a_1 & a_0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \cdots & 0 & a_n & a_{n-1} & \cdots & a_1 & a_0 \\ b_n & b_{n-1} & \cdots & b_1 & b_0 & 0 & \cdots & 0 \\ 0 & b_n & b_{n-1} & \cdots & b_1 & b_0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \cdots & 0 & b_n & b_{n-1} & \cdots & b_1 & b_0 \end{vmatrix}.$$

Elimination Theory



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Institut de Matemàtica
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13 docs

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GRAPE aims at significantly advancing the state of the art in a variety of fields ranging from Computational and Numerical Mathematics to Geometric Modelling and CAD, up to Data Science and Machine Learning, in order to promote game-changing approaches for generating, optimising, and learning 3D shapes.

Research is articulated around three scientific work packages:

1. High-order methods and representations
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Concrete applications include simulation and fabrication, design and visualisation, manufacturing and 3D printing, retrieval and mining, reconstruction and urban planning.

Over 15 PhD-candidates shall benefit from both top-notch research as well as a strong innovation component through a series of international secondments and Network-wide workshops. Innovation and technology transfer is supported by the active participation of SMEs, either as beneficiary, or as associate partners hosting secondments.

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9. SINTEF: Geometric modelling for evolutionary deep learning architecture design
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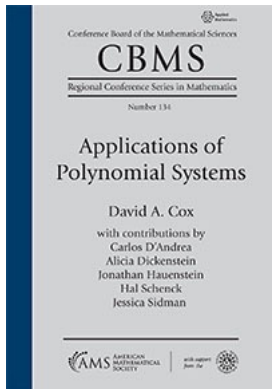
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One book

One book

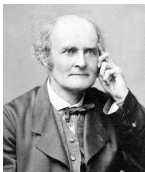


A bit of history

A bit of history

In the problem of **elimination**, one seeks the relationship that must exist between the coefficients of a function or system of functions in order that some particular circumstance (or singularity) can occur.

Cayley, 1864 Nouvelles recherches sur l'élimination et la théorie des courbes



A bit of history

A system of arbitrarily many algebraic equations for $z^0, z', z'', \dots, z^{(n-1)}$, in which the coefficients belong to the rationality domain $(R, R', R'', \dots)$, define the algebraic relations between z and R , whose knowledge and representation are the purpose of the **theory of elimination**.

Kronecker, 1882 Grundzüge einer arithmetischen Theorie der algebraischen Größen



The baby example in elimination

The baby example in elimination

Find “the condition” on
 $a_{10}, a_{11}, a_{20}, a_{21}$ so that the system

$$\begin{cases} a_{10}x_0 + a_{11}x_1 = 0 \\ a_{20}x_0 + a_{21}x_1 = 0 \end{cases}$$

has a solution different from $(0, 0)$

“Elimination”

$$a_{10}x_0 + a_{11}x_1, a_{20}x_0 + a_{21}x_1$$

$$\in \mathbb{K}[a_{10}, a_{11}, a_{20}, a_{21}, x_0, x_1]$$

“Elimination”

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↓

$$a_{10}a_{21} - a_{20}a_{11} \in \mathbb{K}[a_{10}, a_{11}, a_{20}, a_{21}]$$

More general

Find “the condition” for the system

$$\begin{cases} a_{10}x_0 + a_{11}x_1 + \dots + a_{1n}x_n & = 0 \\ a_{20}x_0 + a_{21}x_1 + \dots + a_{2n}x_n & = 0 \\ \vdots & \vdots \\ a_{(n+1)0}x_0 + a_{(n+1)1}x_1 + \dots + a_{(n+1)n}x_n & = 0 \end{cases}$$

More general

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to have a solution different from
 $(0, 0, \dots, 0)$

Another more general

Let $d_1, d_2 \in \mathbb{N}$. Find “the condition”
for the system of polynomials

$$\begin{cases} a_{10}x_0^{d_1} + a_{11}x_0^{d_1-1}x_1 + \dots = 0 \\ a_{20}x_0^{d_2} + a_{21}x_0^{d_2-1}x_1 + \dots = 0 \end{cases}$$

to have a solution different from
 $(0, 0)$

More more more general...

Let $n \in \mathbb{N}$, and $d_1, \dots, d_{n+1} \in \mathbb{N}$, find the condition
for

$$\left\{ \begin{array}{lcl} \sum_{\alpha_0 + \dots + \alpha_n = d_1} a_{1, \alpha_0, \dots, \alpha_n} x_0^{\alpha_0} \dots x_n^{\alpha_n} & = & 0 \\ \sum_{\alpha_0 + \dots + \alpha_n = d_2} a_{2, \alpha_0, \dots, \alpha_n} x_0^{\alpha_0} \dots x_n^{\alpha_n} & = & 0 \\ & \vdots & \\ \sum_{\alpha_0 + \dots + \alpha_n = d_{n+1}} a_{n+1, \alpha_0, \dots, \alpha_n} x_0^{\alpha_0} \dots x_n^{\alpha_n} & = & 0 \end{array} \right.$$

to have a solution different from $(0, 0, \dots, 0)$



Elimination: The general problem

For $\mathbf{a} = (a_1, \dots, a_N)$, $k, n \in \mathbb{N}$ let
 $f_1(\mathbf{a}, x_1, \dots, x_n), \dots, f_k(\mathbf{a}, x_1, \dots, x_n) \in$
 $\mathbb{K}[\mathbf{a}, x_1, \dots, x_n]$. Find conditions on $\mathbf{a}$ such that

$$\left\{ \begin{array}{lll} f_1(\mathbf{a}, x_1, \dots, x_n) & = & 0 \\ f_2(\mathbf{a}, x_1, \dots, x_n) & = & 0 \\ \vdots & \vdots & \vdots \\ f_k(\mathbf{a}, x_1, \dots, x_n) & = & 0 \end{array} \right.$$

has a solution

Solution?

- Depends on the ground field

Solution?

- Depends on the ground field
- There is not necessarily a “closed” condition

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- Depends on the ground field
- There is not necessarily a “closed” condition
- Algorithms??

Easy example

$$\left\{ \begin{array}{lcl} a_{11}x_1 + \dots + a_{1n}x_n & = & 0 \\ a_{21}x_1 + \dots + a_{2n}x_n & = & 0 \\ \vdots & & \vdots \\ a_{kn}x_1 + \dots + a_{kn}x_n & = & 0 \end{array} \right.$$

with $k \geq n$

Easy example

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with $k \geq n$

Conditions: all maximal minors of $(a_{ij})_{1 \leq i \leq k, 1 \leq j \leq n}$
equal to zero

Another “easy” example

$$k = n = 1,$$

$$a_0 + a_1 x_1 + a_2 x_1^2 + \dots + a_d x_1^d = 0$$

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Conditions?

Geometry

$$V = \{(\mathbf{a}, x_1, \dots, x_n) : f_1(\mathbf{a}, x_1, \dots, x_n) = 0, \dots, f_k(\mathbf{a}, x_1, \dots, x_n) = 0\}$$

Geometry

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$$V \subset \mathbb{K}^N \times \mathbb{K}^n$$

$$\pi_1|_V \downarrow \quad \downarrow \pi_1$$

$$\pi_1(V) \subset \mathbb{K}^N$$

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The set of conditions is $\pi_1(V)$ is not necessarily described by zeroes of polynomials

Projective Elimination

(homogeneous polynomials in an algebraically closed field)

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$$\pi_1(V) = \{p_1(\mathbf{a}) = 0, \dots, p_\ell(\mathbf{a}) = 0\}$$

How do we compute the conditions?

How do we compute the conditions?



■ Input: $f_1(\mathbf{a}, \mathbf{x}), \dots, f_k(\mathbf{a}, \mathbf{x})$

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Mertens 1889



Mertens 1889



Set $s := \max \deg(f_i)$, and $G_0, \dots, G_n$ expressions of the form

$G_j(\mathbf{a}, \mathbf{x}) := \sum u_{\alpha,i} \mathbf{x}^\alpha f_i(\mathbf{a}, \mathbf{x})$ of degree s in $\mathbf{x}$ with new parameters $u_{\alpha,i}$.

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Then, “the Kronecker $\mathbf{u}$ -Resultant”

$\text{Res}_{\mathbf{x}}(G_0, \dots, G_n) = \sum_{\beta} P_{\beta}(\mathbf{a}) \mathbf{u}^{\beta}$ gives the conditions $\{P_{\beta}(\mathbf{a})\}$

van der Waerden 1926



van der Waerden 1926



For arbitrary s , we use the “Macaulay matrix”
 $M_s(\mathbf{a})$ such that

$$M_s(\mathbf{a}) \begin{bmatrix} \vdots \\ \mathbf{x}^\beta \\ \vdots \end{bmatrix} = \begin{bmatrix} \vdots \\ \mathbf{x}^\alpha f_i \\ \vdots \end{bmatrix}, \quad |\alpha| = s$$

van der Waerden 1926



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For $s \gg 0$, all maximal minors of $M_s(\mathbf{a})$ vanish iff there is a common solution

Algebra & Geometry

(van der Waerden, 1926)

Algebra & Geometry

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$$\begin{aligned} I(\pi_1(V)) \\ = \\ (\langle f_1, \dots, f_k \rangle : \langle x_0, \dots, x_n \rangle^\infty) \end{aligned}$$

Algebra & Geometry

(van der Waerden, 1926)

$$\begin{aligned} & I(\pi_1(V)) \\ &= \\ & (\langle f_1, \dots, f_k \rangle : \langle x_0, \dots, x_n \rangle^\infty) \cap \mathbb{K}[\mathbf{a}] \end{aligned}$$

The “elimination ideal”

But what if...



But what if...



- the polynomials are not homogeneous?

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- the polynomials are not homogeneous?
- $\mathbb{K}$ is not algebraically closed?

$\mathbb{K}$ is the problem?

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- Embed $\mathbb{K} \hookrightarrow \overline{\mathbb{K}}$ and work there

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- . . .

Homogeneous vs non homogeneous

Homogeneous vs non homogeneous

Analogy with Linear Algebra...

$$\begin{array}{c} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 0 & 0 & -1 & -1 \\ 0 & 1 & 1 & 2 \end{array} \right] \\ \downarrow \\ \left[\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & -1 & -1 \end{array} \right] \end{array}$$

Generalization of the determinant?

$$V = \{(\mathbf{a}, x_0, x_1, \dots, x_n) : f_1(\mathbf{a}, x_0, x_1, \dots, x_n) = 0, \dots, f_{n+1}(\mathbf{a}, x_0, x_1, \dots, x_n) = 0\}$$

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One hopes!

Example 1

$$\left\{ \begin{array}{l} a_{00}x_0 + a_{01}x_1 + \dots + a_{0n}x_n = 0 \\ a_{10}x_0 + a_{11}x_1 + \dots + a_{1n}x_n = 0 \\ \qquad \qquad \qquad \vdots \qquad \qquad \qquad \vdots \qquad \vdots \\ a_{n0}x_0 + a_{n1}x_1 + \dots + a_{nn}x_n = 0 \end{array} \right.$$

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$$p_1(a) = \det(a_{ij})$$

Example 2

$$\begin{cases} f_1 = a_{10}x_0^{d_1} + a_{11}x_0^{d_1-1}x_1 + \dots + a_{1d_1}x_1^{d_1} \\ f_2 = a_{20}x_0^{d_2} + a_{21}x_0^{d_2-1}x_1 + \dots + a_{2d_2}x_1^{d_2} \end{cases}$$

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$$\text{Res}(f_1, f_2) = \det \begin{pmatrix} a_{10} & a_{11} & \dots & a_{1d_1} & 0 & \dots & 0 \\ 0 & a_{10} & \dots & a_{1d_1-1} & a_{1d_1} & \dots & 0 \\ \vdots & \vdots & \ddots & \dots & \dots & \ddots & \vdots \\ 0 & 0 & \dots & a_{10} & \dots & \dots & a_{1d_1} \\ a_{20} & a_{21} & \dots & a_{2d_2} & 0 & \dots & 0 \\ 0 & a_{20} & \dots & a_{2d_2-1} & a_{2d_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \dots & \dots & \ddots & \vdots \\ 0 & 0 & \dots & a_{20} & \dots & \dots & a_{2d_2} \end{pmatrix}$$

Example 3

$$\left\{ \begin{array}{l} f_1 = \sum_{\alpha_0 + \dots + \alpha_n = d_1} a_{1, \alpha_0, \dots, \alpha_n} x_0^{\alpha_0} \dots x_n^{\alpha_n} \\ f_2 = \sum_{\alpha_0 + \dots + \alpha_n = d_2} a_{2, \alpha_0, \dots, \alpha_n} x_0^{\alpha_0} \dots x_n^{\alpha_n} \\ \vdots \\ f_{n+1} = \sum_{\alpha_0 + \dots + \alpha_n = d_{n+1}} a_{n+1, \alpha_0, \dots, \alpha_n} x_0^{\alpha_0} \dots x_n^{\alpha_n} \end{array} \right.$$

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$$\text{Res}_{d_1, \dots, d_n}(f_1, f_2, \dots, f_{n+1})$$

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$\text{Res}_{d_1, \dots, d_n}(f_1, f_2, \dots, f_{n+1})$
Macaulay/dense/classical resultant

No-example

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$$p_3(\mathbf{a}) = a_{20}^2a_{12}^2 - a_{20}a_{21}a_{11}a_{12} - 2a_{20}a_{22}a_{10}a_{12} + a_{20}a_{22}a_{11}^2 + a_{21}^2a_{10}a_{12} - a_{21}a_{22}a_{10}a_{11} + a_{22}^2a_{10}^2$$

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“Triangulating” a system

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Two ways:

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Two ways:

- Gröbner Bases (w.r.t. “lex”)

“Triangulating” a system

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- Triangular Decomposition

“Triangulating” a system

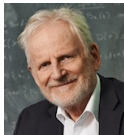
Two ways:

- Gröbner Bases (w.r.t. “lex”)
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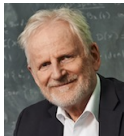
Both use some kind of **division** of
polynomials

$$\begin{array}{rcl} a_1: & & y \\ a_2: & & -1 \\ xy+1 & & \sqrt{xy^2+1} \\ y+1 & & \\ \hline & & xy^2+y \\ & & \underline{-y+1} \\ & & -y-1 \end{array}$$

Gröbner Bases

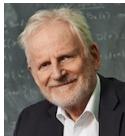


Gröbner Bases



Every ideal in $\mathbb{K}[\mathbf{a}, \mathbf{x}]$ has a finite set
of generators $I = \langle g_1, \dots, g_N \rangle$

Gröbner Bases



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of generators $I = \langle g_1, \dots, g_N \rangle$
 $\{g_1, \dots, g_N\}$ is a **Gröbner basis** iff
$$g \in I \iff r_{g_1, \dots, g_N}(g) = 0$$

Gröbner Bases and Elimination

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In $\mathbb{K}[a, x]$, if $a \prec x$, then

Gröbner Bases and Elimination

$$\begin{array}{l} \text{In } \mathbb{K}[\mathbf{a}, \mathbf{x}], \text{ if } \mathbf{a} \prec \mathbf{x}, \text{ then} \\ G = GB(I) \implies G \cap \mathbb{K}[\mathbf{a}] = \\ \quad GB(I \cap \mathbb{K}[\mathbf{a}]) \end{array}$$

Gröbner Bases and Elimination

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And $I \cap \mathbb{K}[\mathbf{a}]$ is the (affine) ideal of
the projection

Triangular sets



Triangular sets



- Characteristic set's method (J.F. Ritt - 1940's)

Triangular sets



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- Wu's method (Wenjun Wu - 1970's)

Triangular sets

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Membership to I is easily tested

The “dictionary” of elimination

Linear

Polynomial

The “dictionary” of elimination

Linear

Gauss elimination

Polynomial

Gröbner Bases

The “dictionary” of elimination

Linear

Gauss elimination

Triangulation

Polynomial

Gröbner Bases

Triangular sets

The “dictionary” of elimination

Linear

Gauss elimination

Triangulation

Determinants

Polynomial

Gröbner Bases

Triangular sets

Resultants

The “dictionary” of elimination

Linear

Gauss elimination

Triangulation

Determinants

Cramer's rule

...

Polynomial

Gröbner Bases

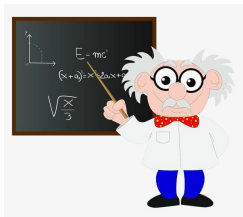
Triangular sets

Resultants

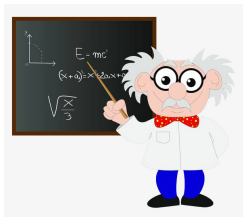
u-resultants

...

And we will focus on Resultants!

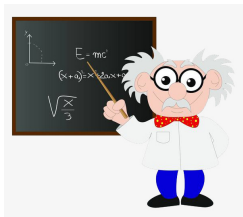


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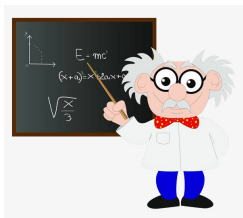
■ Univariate Resultant

And we will focus on Resultants!



- Univariate Resultant
- Multivariate Resultants

And we will focus on Resultants!



- Univariate Resultant
- Multivariate Resultants
- Sparse Resultants

Univariate Resultants

$$\begin{cases} f_1 = a_{10}x_0^{d_1} + a_{11}x_0^{d_1-1}x_1 + \dots + a_{1d_1}x_1^{d_1} \\ f_2 = a_{20}x_0^{d_2} + a_{21}x_0^{d_2-1}x_1 + \dots + a_{2d_2}x_1^{d_2} \end{cases}$$

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What is the resultant of f_1 and f_2 ?



Algebraic Definitions

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$\text{Res}(f_1, f_2)$ is:

- the “condition” to test if $\gcd(f_1, f_2) = 1$ (Sylvester)
- One of the (two) generators of the elimination ideal

$$\langle f_1(x_0, 1), f_2(x_0, 1) \rangle \cap \mathbb{Z}[a_{10}, \dots, a_{1d_1}, a_{20}, \dots, a_{2d_2}]$$

Geometry

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$$V = \{(\alpha_{10}, \dots, \alpha_{2d_2}; p_0 : p_1) : f_1(\alpha, p_0, p_1) = f_2(\alpha, p_0, p_1) = 0\}$$

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$\text{Res}(f_1, f_2) \in \mathbb{K}[a_{10}, \dots, a_{2d_2}]$ should be the equation of $\pi_1(V)$

Does Algebra meet Geometry?



Does Algebra meet Geometry?



■ gcd

Does Algebra meet Geometry?



- gcd
- elimination ideal

Does Algebra meet Geometry?



- gcd
 - elimination ideal
 - equation of a hypersurface
- ?

gcd

gcd

For $\tilde{f}_1, \tilde{f}_2 \in \mathbb{K}[x_0, x_1]$ homogeneous of
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gcd

For $\tilde{f}_1, \tilde{f}_2 \in \mathbb{K}[x_0, x_1]$ homogeneous of degrees d_1, d_2 to have a nontrivial common factor the map

$$\begin{array}{ccc} \mathbb{K}[x_0, x_1]_{d_2-1} \oplus \mathbb{K}[x_0, x_1]_{d_1-1} & \xrightarrow{\phi} & \mathbb{K}[x_0, x_1]_{d_1+d_2-1} \\ (g_1, g_2) & \mapsto & g_1 \tilde{f}_1 + g_2 \tilde{f}_2 \end{array}$$

fails to be an isomorphism

Matrix of ϕ

Matrix of ϕ

$$\begin{pmatrix} a_{10} & a_{11} & \dots & a_{1d_1} & 0 & \dots & 0 \\ 0 & a_{10} & \dots & a_{1d_1-1} & a_{1d_1} & \dots & 0 \\ \vdots & \vdots & \ddots & \dots & \dots & \ddots & \vdots \\ 0 & 0 & \dots & a_{10} & \dots & \dots & a_{1d_1} \\ a_{20} & a_{21} & \dots & \dots & a_{2d_2} & \dots & 0 \\ 0 & a_{20} & \dots & \dots & a_{2d_2-1} & \dots & 0 \\ \vdots & \vdots & \ddots & \dots & \dots & \ddots & \vdots \\ 0 & 0 & \dots & a_{20} & \dots & \dots & a_{2d_2} \end{pmatrix}$$

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$$\text{Res}(f_1(\lambda_0 x_0, \lambda_1 x_1), f_2(\lambda_0 x_0, \lambda_1 x_1)) = (\lambda_0 \lambda_1)^{d_0 d_1} \text{Res}(f_1, f_2)$$

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(exercise)

Geometry

Geometry

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■ Is $\pi_1(V)$ a hypersurface?

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- Is $\pi_1(V)$ a hypersurface?
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- Is $\pi_1|_V$ birational?

$\pi_1(V)$ is a rational hypersurface

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■ ψ is onto

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$\pi_1(V)$ is an irreducible hypersurface!

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Algebra meets Geometry!

Poisson's formula

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- $\implies \boxed{a_{2d_2}^{d_1} \prod_{f_2(\xi,1)=0} f_1(\xi, 1) = \text{Res}(f_1, f_2)}$

Corollary: Multiplicativity

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$$\text{Res}(f_1 \cdot f_1', f_2) = \text{Res}(f_1, f_2) \cdot \text{Res}(f_1', f_2)$$

Other determinantal formulae

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Assume $d_1 = d_2$

$$\begin{aligned} f_1(x, 1)f_2(y, 1) - f_1(y, 1)f_2(x, 1) \\ = (x - y) \sum_{0 \leq i, j < d_1} b_{ij} x^i y^j \end{aligned}$$

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Other “hybrid” formulae (GKZ)

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$$\tilde{f}_1, \tilde{f}_2 \in \mathbb{Z}[x_0, x_1], \text{Res}(\tilde{f}_1, \tilde{f}_2) = m \in \mathbb{Z}$$

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What if $p \mid m$??

Theorem

Gomez-Perez, Gutierrez, Ibeas, Sevilla
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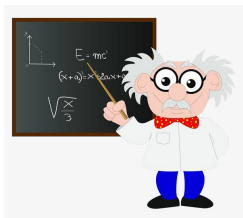
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(Exercise)

See you tomorrow!



- Multivariate Resultants
- Sparse Resultants

<http://www.ub.edu/arcades/notes.html>