



### **Graph-Based Segmentation Methods.** From a Classical Approach to Graph Convolutional Networks

Dr Esmeralda Ruiz Pujadas; 18th October 2022

euCanSHare T5.5

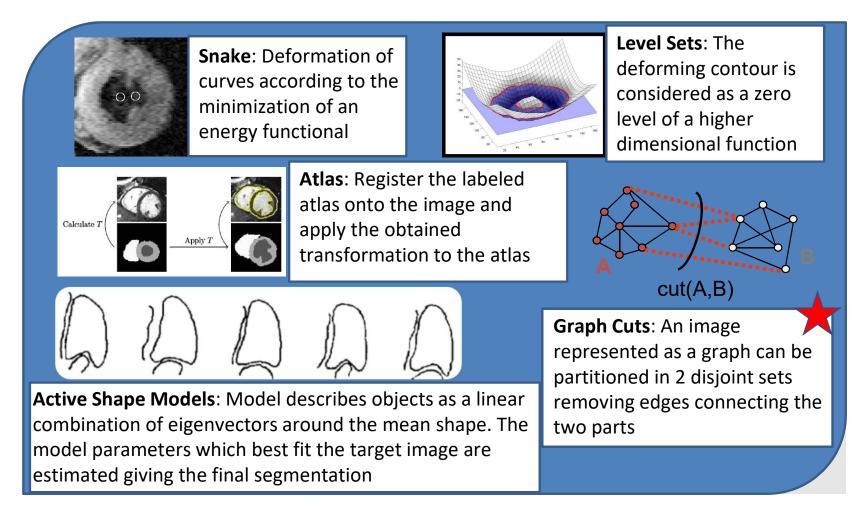






### **1 – Review of Traditional** Segmentation Approaches





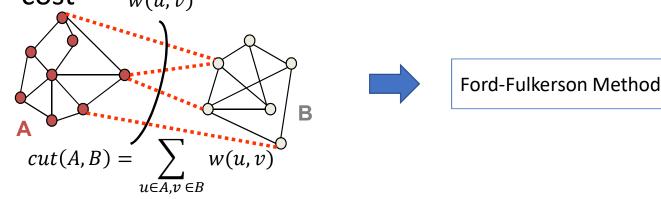




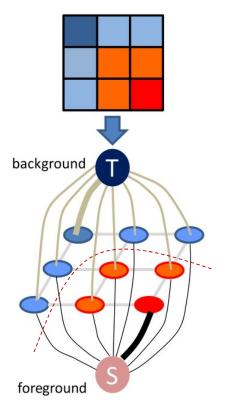
### 2 – Introduction to Graph-based Segmentation Methods



- Image is represented as a graph:
  - Pixels: nodes
  - Edges: weights indicating similarity
- A graph can be partitioned in 2 disjoint sets removing edges connecting the two parts (red dotted line)
- Optimal bi-partitioning is the one that minimizes the cut cost w(u, v)





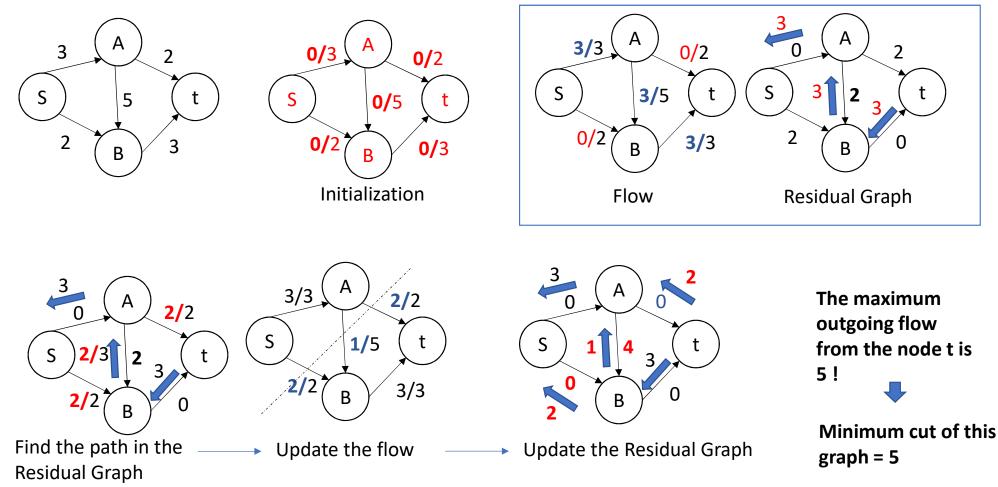


[Shiyan Pang et al., Sensors, 2018]



# 

### ቻ Ford-Fulkerson Method

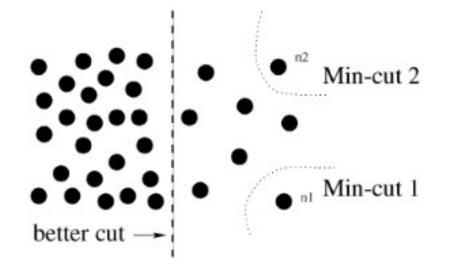


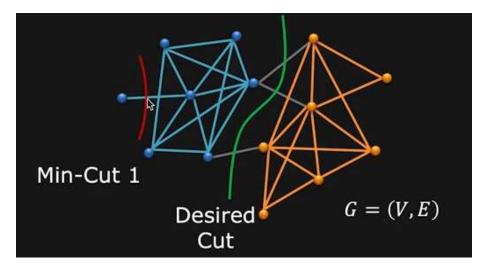
[T.Donwey, Donwey webpage, 2019]





• It can be biased toward producing a small contour.



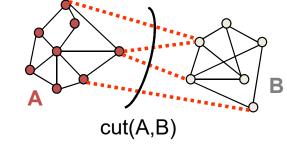


[Shi and Malik, PAMI, 2000 ;Shree Nayar, First Principles of CV, 2021]





- Systematic global energy minimization
- Robust to initialization
- No seeds required
- Limited number of parameters



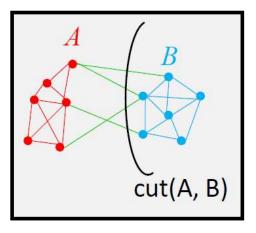
- Limitation: Incorporation of shape prior is challenging
  - The formulation must be changed





# Normalized Cuts Partition

- An image transformed into a graph:
  - Nodes: Voxels of the image
  - Edges: Weights (W) between voxels.
- Balance between:
  - Cost of the boundary
  - Size of regions

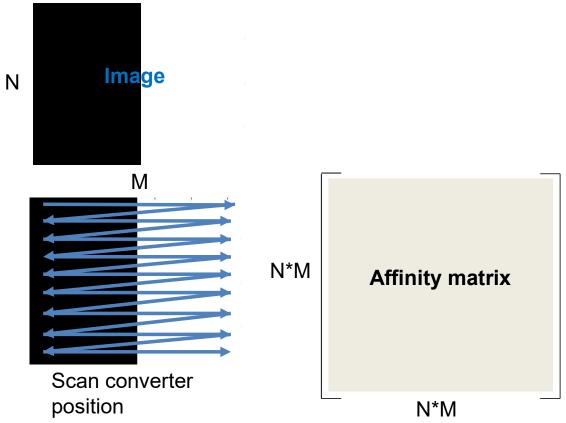


• Optimal bi-partitioning is the one that minimizes the cut cost [Shi and Malik, PAMI, 2000]

assoc(A,V) are the total weights of edges connecting nodes within A. (Equiv. to B)



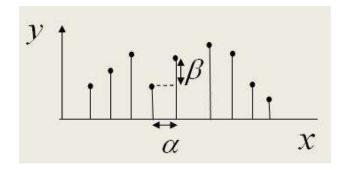
• Construct the Affinity matrix (W) as follows:







• Calculate the weights as follows:



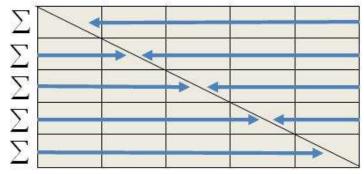
• Product of distances of spatial and intensity Gaussians

$$W_{ij} = G_{\sigma_x}(\alpha) * G_{\sigma_y}(\beta)$$



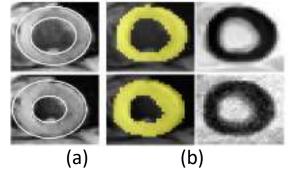


• Diagonal matrix (D):



Weight matrix

- Eigenvector decomposition:
  - Laplacian Matrix = (D-W)
- Choose the eigenvector with the second smallest eigenvalue
- Back-project to the image
- Thresholding

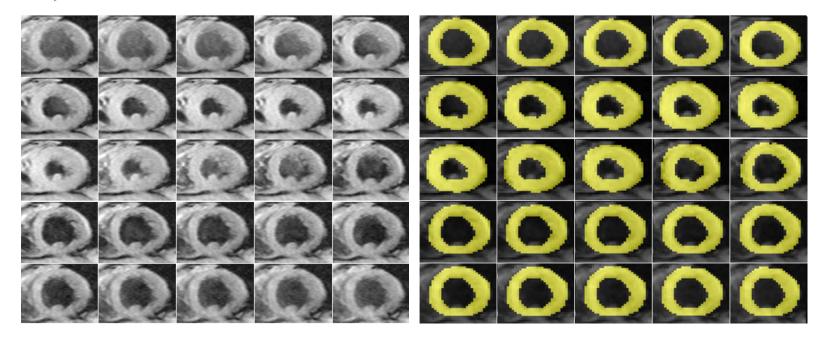


(a) Original image with single prior. (b) The proposed method and its normalized cut.





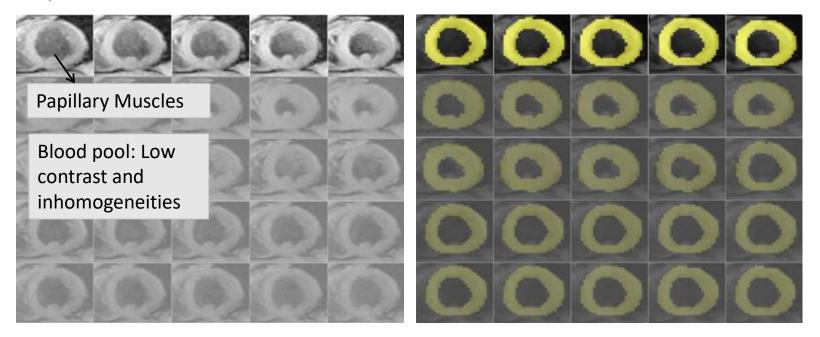
• 25 cardiac MRI images of one volunteer over 1 ECG cycle







• 25 cardiac MRI images of one volunteer over 1 ECG cycle

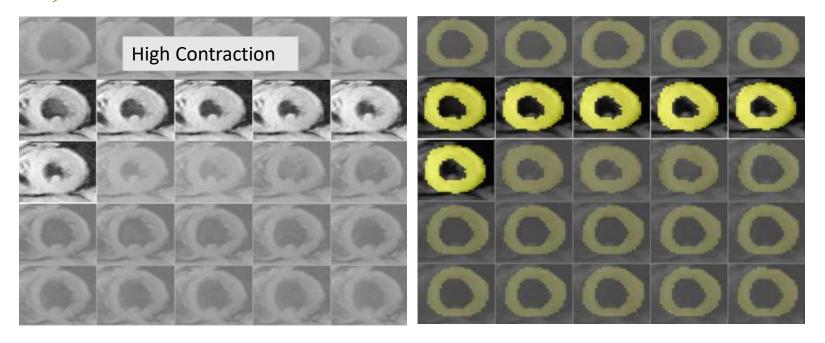


[E.Ruiz et.al, TIP, 2013]





# 25 cardiac MRI images of one volunteer over 1 ECG cycle

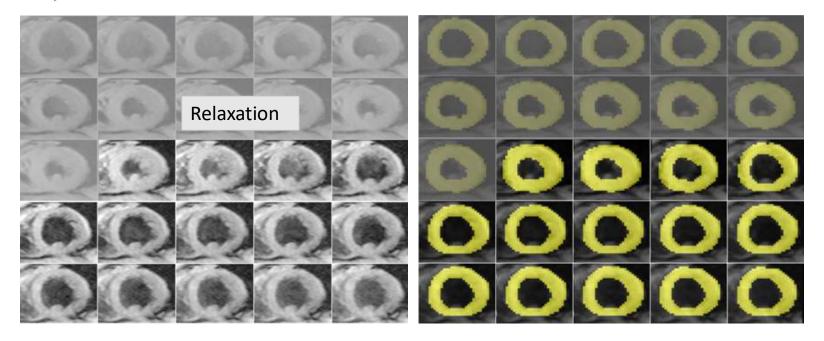


[E.Ruiz et.al, TIP, 2013]





25 cardiac MRI images of one volunteer over 1 ECG cycle

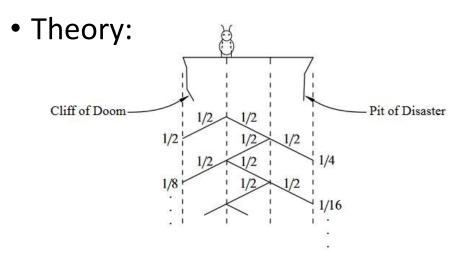


[E.Ruiz et.al, TIP, 2013]





- Random walks algorithm is a graph-based segmentation method. It is a good candidate due to its numerous advantages: [Leo Grady, PAMI, 2006]
  - Robust to noise
  - Robust to weak edges
  - Overcomes the drawbacks of graph cuts



he falls off the Cliff of Doom on the left side with probability:

$$\frac{1}{2} + \frac{1}{8} + \frac{1}{32} + \dots = \frac{1}{2} \left( 1 + \frac{1}{4} + \frac{1}{16} + \dots \right)$$
$$= \frac{1}{2} \cdot \frac{1}{1 - \frac{1}{4}}$$
$$= \frac{2}{3}.$$

Pit of Disaster on the right side with probability:

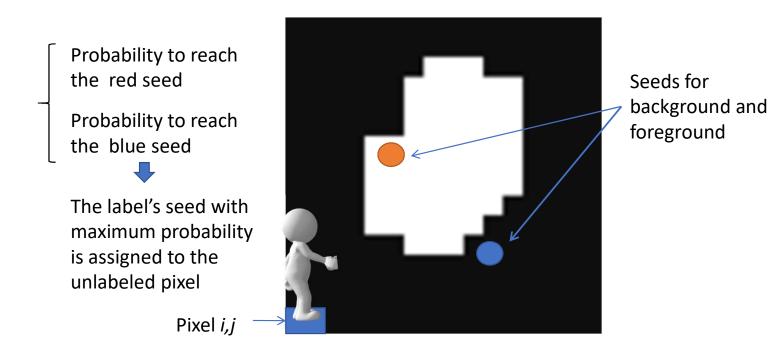
$$\frac{1}{4} + \frac{1}{16} + \frac{1}{64} + \ldots = \frac{1}{3}.$$

[Source: mitopencourseware]



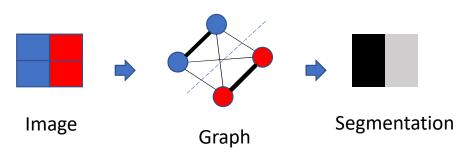


 Determine the probability that a random walker starting at each unlabeled pixel will first reach one of the seeds

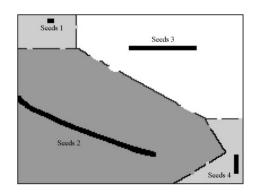




- Assign each pixel to the label for which it is most likely to reach first
- Image represented as a graph:
  - Pixels are nodes
  - Edges encode node similarity based on image features (weights)
- Small weights indicate less similarity and vice versa
- Partitions a graph according to the node similarity (biased by edges)



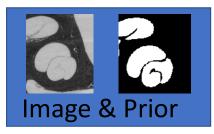


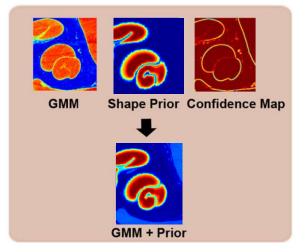






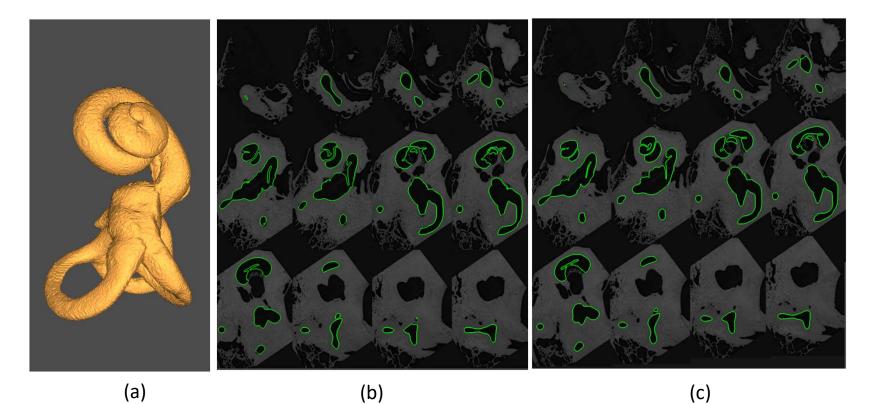
- No seeds are required unlike the standard random walks
- Probability distribution is introduced into the random walks [Leo Grady, CVPR, 2005]
- The new formulation allows a flexible way to introduce shape priors











Inner Ear segmentation. (a) Segmentation in 3D. (b) Slices of the 3D segmentation. (c) Ground truth

[E.Ruiz et.al., Mach Vis Appl. 2015]





### 3 – Coexistence with Deep Learning Methods



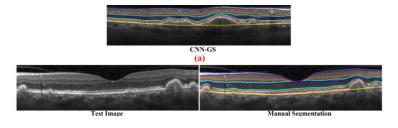
# Deep Learning and Graph Search

Automatic segmentation of nine retinal layer boundaries in OCT images of non-exudative AMD patients using deep learning and graph search

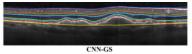
#### LEYUAN FANG,<sup>1,2,\*</sup> DAVID CUNEFARE,<sup>1</sup> CHONG WANG,<sup>2</sup> ROBYN H. GUYMER,<sup>3</sup> SHUTAO LI,<sup>2</sup> AND SINA FARSIU<sup>1,4</sup>

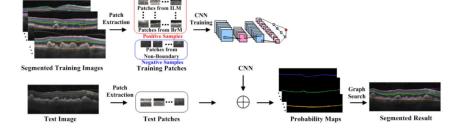
<sup>1</sup>Departments of Biomedical Engineering Duke University, Durham, NC 27708, USA <sup>2</sup>College of Electrical and Information Engineering, Hunan University, Changsha 410082, China <sup>3</sup>Centre for Eye Research Australia University of Melbourne, Department of Surgery, Royal Victorian Eye and Ear Hospital, Victoria 3002, Australia <sup>4</sup>Department of Ophthalmology, Duke University Medical Center, Durham, NC 27710, USA

\*leyuan.fang@duke.edu









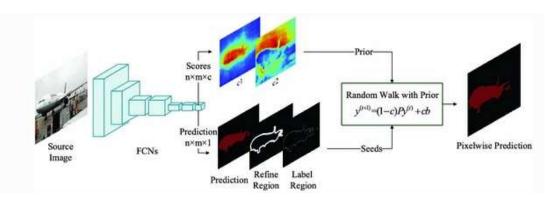


# Deep Learning and Random Walks

#### Semantic Segmentation Using Fully Convolutional Networks and Random Walk with Prediction Prior

Xiaoyu Lei<sup>( $\boxtimes$ )</sup>, Yao Lu<sup>( $\boxtimes$ )</sup>, Tingxi Liu<sup>( $\boxtimes$ )</sup>, and Xiaoxue Shi<sup>( $\boxtimes$ )</sup>

Beijing Laboratory of Intelligent Information Technology, School of Computer Science, Beijing Institute of Technology, Beijing 100081, China {leixiaoyu,vis\_yl,liutx,shixiaoxue}@bit.edu.cn



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(a) Source	(b) GT	(c) Deeplab	(d) Deeplab+CRF	(e) Deeplab+RW

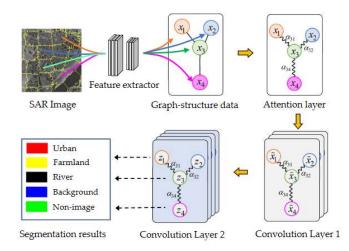


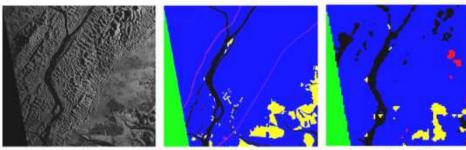
# Graph Convolution Network

#### Attention Graph Convolution Network for Image Segmentation in Big SAR Imagery Data

Fei Ma <sup>1</sup><sup>(0)</sup>, Fei Gao <sup>1,\*</sup><sup>(0)</sup>, Jinping Sun <sup>1</sup><sup>(0)</sup>, Huiyu Zhou <sup>2</sup> and Amir Hussain <sup>3</sup><sup>(0)</sup>

- <sup>1</sup> School of Electronic and Information Engineering, Beihang University, Beijing 100191, China; mafeimf@buaa.edu.cn (F.M.); sunjinping@buaa.edu.cn (J.S.)
- <sup>2</sup> Department of Informatics, University of Leicester, Leicester LE1 7RH, UK; hz143@leicester.ac.uk
- <sup>3</sup> Cognitive Big Data and Cyber-Informatics (CogBID) Laboratory, School of Computing, Edinburgh Napier University, Edinburgh EH10 5DT, UK; A.Hussain@napier.ac.uk
- \* Correspondence: 08060@buaa.edu.cn; Tel.: +86-136-8144-4428





(a) Test image

(b) Ground Truth

(c) AGCN



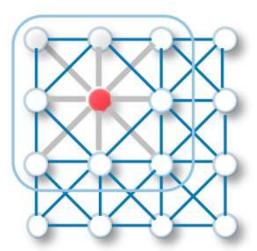


### 3 – Graph Convolutional Methods

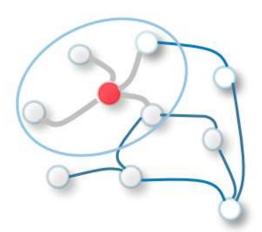




- It can work on data with underlying non-regular structures
- The insertion of Adjacency Matrix (A) enable the model to learn the features of neighboring nodes



2D Convolutional Neural Networks

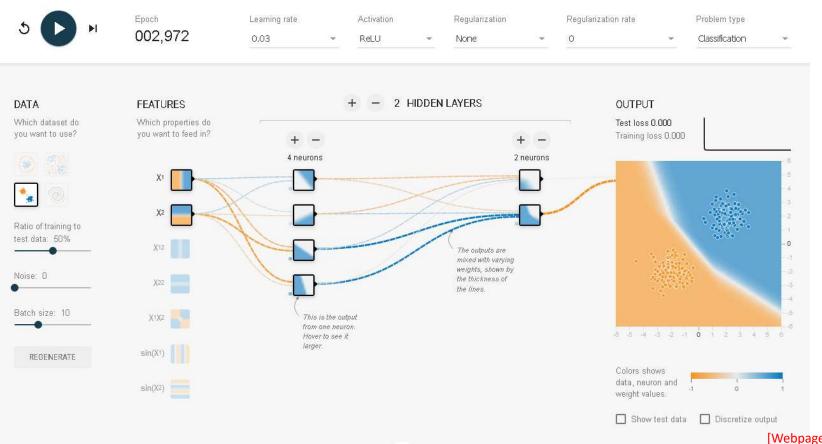


Graph Convolution Network



## Deep Learning Introduction

PTAS PERF

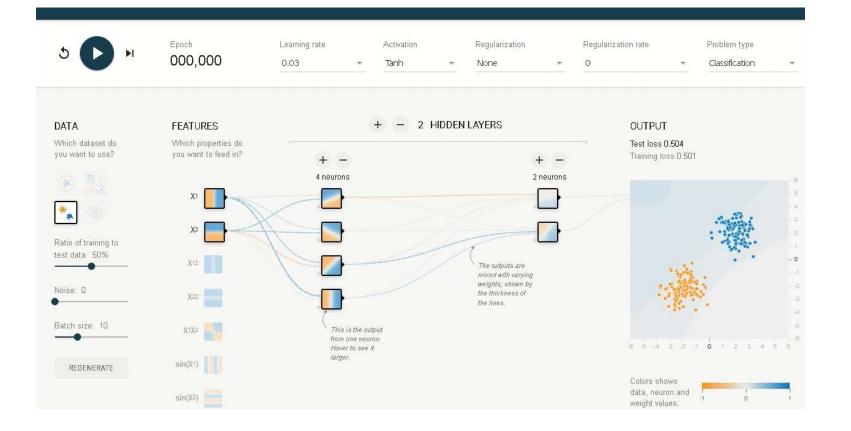


<sup>[</sup>Webpage: http://playground.tensorflow.org]



# Deep Learning Introduction

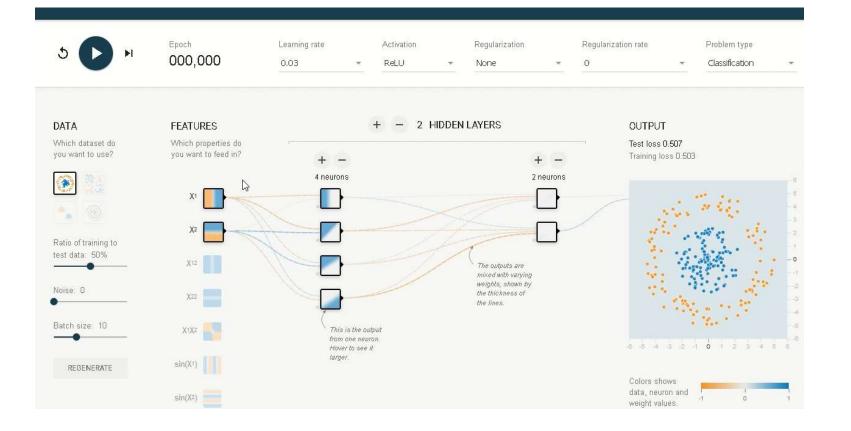
PTAS PERFY





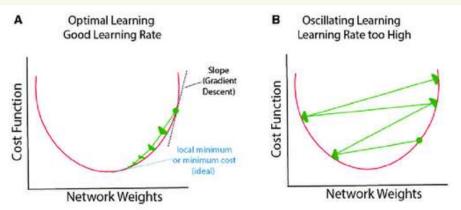
# Deep Learning Introduction

PTAS PERFY





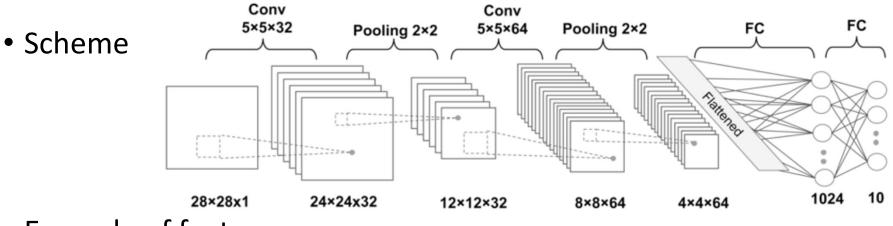
 Learning rate: controls how much change the model in response estimated error each time model weights are updated



- **Epochs:** number of times that the deep learning algorithm will work through the entire training dataset
- Bath size: subdivide the training data into batches to pass it to the network
- Activation function: to propagate forward the output of the node







• Example of features



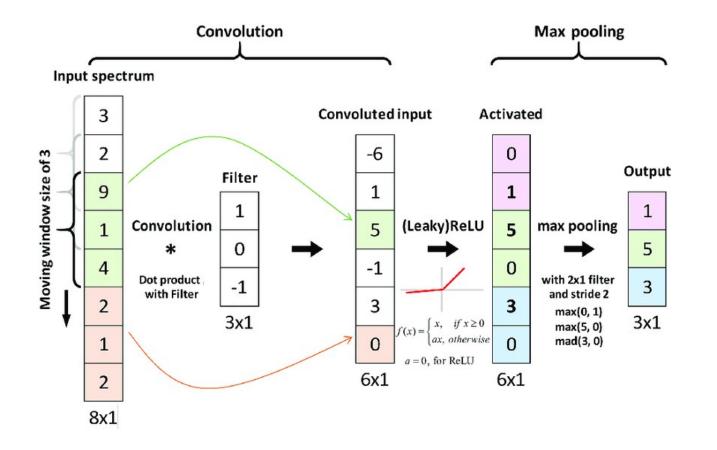


Medium level

High level

BCN

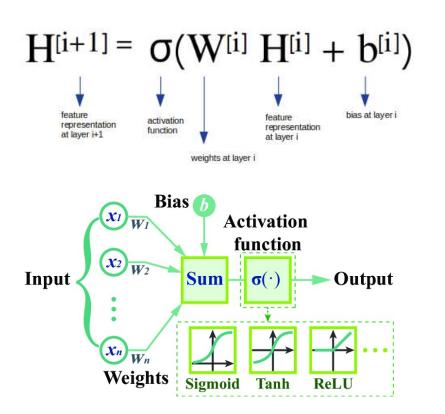




[Wooje Lee et al., J Raman Spectroscopy, 2019]



# Graph Convolution via Fast Approximate Spectral Graph



Forward Pass in Neural Networks

 $H^{[i+1]} = \sigma(W^{[i]} H^{[i]} A^{*})$   $\downarrow$ Normalized Adjacency Matrix considering self-loop  $H^{[i+1]} = \sigma(\tilde{D}^{\frac{-1}{2}}\tilde{A} \tilde{D}^{\frac{-1}{2}}H^{[i]} W^{[i]})$   $\tilde{A} = A + Id$ 

[Inneke Mayachita, towardsdatascience,2020; Zhengjing Ma et al., Earth-Science Reviews ,2021]





### **3 – Conclusion and Discussion**





- Graph-Based Segmentation Methods
  - A large number of samples is not required
  - The incorporation of priors requires to change the formulation
  - The representation of the image is sparse
- Deep Learning Methods
  - A big number of datasets is required
  - The use of deep learning methods is straightforward
- Hybrid
  - Combination of information obtained by graphs and deep learning techniques
  - It can learn features representation even before training





### Thank you for your attention