A CONVOLUTIONAL • PERSISTENCE • TRANSFORM

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The TDA Pipeline (part of)

- Describe what this step usually consists of.
- Explain why the standard approach is limited.
- Propose a new approach.
- Prove that new approach is better.
- Try the new approach on real data and see the results.



Converting Images to Filtered Simplicial Complexes

- Represent the image grid using a cubical complex.
- Pixels are either vertices or top-dimensional cells. Pixel intensity defines a function on vertices/top-dim cells.
- Extend to the rest of the complex using lower/upper-star.
- Use Freudenthal triangulation .



The two constructions give different but equivalent diagrams.

The Persistent Homology of Dual Digital Image Constructions

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Limitations of Image TDA (Persistence)

- Persistence is unstable to outliers.
- Many different images can have the same persistence. In other words, image persistence is *lossy / not injective*.
- Image persistence is not customizable. You get a single invariant for each image, and you cannot adapt that invariant depending on the context.
- Some images need *more preprocessing* for topology to be useful.







Adding an Intermediate Step: Preprocess with Convolutions



Smoothing and Sharpening Convolution Kernels



Convolutions + Persistence = Convolutional Persistence



Properties of Convolutional Persistence

- Using the right filters, convolutional persistence is *more stable to outliers*.
- A convolved image is often much smaller than the original. This greatly **speeds up** persistence computations.



• For any two images, there exists some filter that can tell them apart – meaning that convolving with that filter produces different persistence diagrams. (*injectivity*)

The Proof of Injectivity

We use another construction from applied topology: the persistent homology transform.

For a vector $v \in \mathbb{S}^{d-1} \subset \mathbb{R}^d$, define the function $f_v = \langle \cdot, v \rangle$. Given $X \subset \mathbb{R}^d$, define PHT(S) be the function sending vectors $v \in \mathbb{S}^{d-1}$ to their corresponding persistence diagrams $PH(X, f_v)$.

Theorem (Turner, Mukherjee, Boyer, Ghrist, Levanger, Mai, Curry):

The PHT is injective, i.e. PHT(X) = PHT(Y) implies X = Y.



Relating Convolutions and the PHT



Define $\vec{g} = (g_{11}, g_{12}, g_{21}, g_{22}).$ Observe: For a vertex $r \in R$, we have $(f * g)(r) = \iota_f(r) \cdot \hat{g}.$

The continuously embedded grid.

The discrete, abstract grid.

 $(f_{n}, f_{12}, f_{21}, f_{22})$ $(f_{23}, f_{24}, f_{33}, f_{34})$ (generically)

Continuous filtration $\langle \cdot, \vec{g} \rangle$.

Discrete filtration f * g.

Due to a well-known result in persistence theory, these two filtrations, which agree on the vertex set, produce identical persistence diagrams.

 $PHT(\iota_f(R))$ evaluated at \vec{g} . = Convolutional persistence for filter g.

Using the embedding ι_f , convolutional persistence can be viewed as a special case of the PHT, and so inherits its injectivity properties. This can easily be generalized to high-dimensional images with multiple channels.

Important Observation: No extra information is gained by using filters that are orthogonal to the patches found in the images. In natural images, the space of patches has large codimension, significantly reducing the number of filters needed.





Convolutional Persistence Pipeline

- Given: collection of images.
- Pick: family of *n* filters *G*. Which filters?
- For each image, convolve with G to get n new images, and then compute persistence, obtaining n persistence diagrams.
- Vectorize the collection of diagrams. How to vectorize?
- Use vectors in Machine Learning model. Which model?

Pipeline Parameters

Filters

Vectorizations

Models

- 1. [1] trivial filter.
- 2. Standard image processing filters.
- 3. Eigenfilters: Apply PCA to space of image patches and take random linear combinations of top eigenvectors.
- 4. Random filters.

- 1. Persistence Images.
- 2. Total persistence.
- A. Concatenating vectors
- B. Averaging vectors

- 1. k-NN.
- 2. Boosted Tree.
- 3. Neural Network.





Classification Tasks

MNIST

A selection from the 64-dimensional digits dataset

UCI digits

0123450113 4501234505 5504135100 2220123333 4415052204 1324431314 13245544004 2225544004 2225544005 2345042345 0123450555

https://archive.ics.uci.edu/ml/datasets/Optic

al+Recognition+of+Handwritten+Digits http://yann.lecun.com/exdb/mnist/ https://www.kaggle.com/datasets/gpreda/chinese-mnist https://www.kaggle.com/datasets/anurags397/hindi-mnist-data



Chinese Digits



Devanagari "MNIST"



Kuramoto Sivanshinsky Examples



Digits Dataset



MNIST Dataset



Chinese Digits Dataset



Devanagari Dataset



Kuramoto Sivashinsky Dataset 1.0 Vectorization Image Con Image Av TotPers Con TotPers Av 0.8 Tree iree Tree ree Average Accuracy 0.6 Tree Tree īree Tree Tree Tree **NN** Tree NN 0.4 0.2 0.0 Standard Filters EigenFilters Trivial 5 Random 25 Random Experiments

Observations

- Convolution persistence significantly outperforms ordinary image persistence. Concatenating vectors and using deep learning seems to give the best accuracy.
- Eigenfilters are best, but random filters also work really well. Why?
- Total persistence is a very effective vectorization.

Why??

More questions...

- How does the filter size affect the results above?
- What happens if you use other vectorizations: Euler curves, persistence landscapes, etc. or allow learnable vectorizations?
- Can you get better accuracy scores by incorporating feature engineering and model tuning?
- Can you learn optimal filters using the training data?
- Run these experiments on more complex, higher-dimensional, or multi-channel data where topology is already known to be useful.
- There are many technical results and open questions surrounding the PHT. Can these be improved/answered for convolutional persistence? https://arxiv.org/abs/2208.02107

https://arxiv.org/abs/2208.02107 https://github.com/yesolomon/convpers

